



Mitigating the Exposure Bias in Sentence-Level Grapheme-to-Phoneme (G2P) Transduction

Eunseop Yoon^{1*}, Hee Suk Yoon^{1*}, Dhananjaya Gowda², SooHwan Eom¹, Daehyeok Kim¹,
John Harvill³, Heting Gao³, Mark Hasegawa-Johnson³, Chanwoo Kim², and Chang D. Yoo^{1†}

¹Korea Advanced Institute of Science and Technology (KAIST), Republic of Korea

²University of Illinois at Urbana-Champaign, USA, ³Samsung Electronics, Republic of Korea

{esyoon97, hskyoon, sean1105, kimshine, cd.yoo}@kaist.ac.kr,
{d.gowda, chanw.com}@samsung.com, {harvill12, hgao17, jhasegaw}@illinois.edu

Abstract

Text-to-Text Transfer Transformer (T5) has recently been considered for the Grapheme-to-Phoneme (G2P) transduction. As a follow-up, a tokenizer-free byte-level model based on T5 referred to as ByT5, recently gave promising results on word-level G2P conversion by representing each input character with its corresponding UTF-8 encoding. Although it is generally understood that sentence-level or paragraph-level G2P can improve usability in real-world applications as it is better suited to perform on heteronyms and linking sounds between words, we find that using ByT5 for these scenarios is nontrivial. Since ByT5 operates on the character level, it requires longer decoding steps, which deteriorates the performance due to the exposure bias commonly observed in auto-regressive generation models. This paper shows that the performance of sentence-level and paragraph-level G2P can be improved by mitigating such exposure bias using our proposed loss-based sampling method.

Index Terms: grapheme-to-phoneme conversion, phonetic transcription, ByT5, exposure bias

1. Introduction

Grapheme-to-phoneme (G2P) transduction is essential for various applications that require phonetic lexicon, including automatic speech recognition (ASR) [1] and text-to-speech synthesis (TTS) [2]. There are two primary types of G2P tasks: word-level and sentence-level. In word-level G2P, the goal is to predict the pronunciation of a single word, whereas sentence-level G2P¹ involves predicting the pronunciations of all the words in a sentence. The latter is a more challenging task as it requires modeling context-dependent pronunciation variations of words (i.e., heteronyms) and linking sounds between words, making it more suitable for real-world applications.

With the recent advancements in deep learning, transformer-based encoder-decoder language models, such as the Text-to-Text Transfer Transformer (T5) [3], have emerged as a powerful tool for the G2P conversion [4, 5, 6] where they learn to map input sequences (i.e., graphemes) to their corresponding output sequences (i.e., phonemes). Particularly, ByT5, a byte-level model based on T5, has been introduced as a token-free language model representing each character in a sequence with its corresponding UTF-8 encoding. Previous research shows that ByT5 gives promising results on word-level G2P conversion [6], outperforming traditional token-based models. In this paper, we take a step towards extending ByT5 to the sentence-level G2P conversion.

*Equal contribution

†Corresponding author

¹For simplicity, sentence-level refers to both the sentence and paragraph-level (i.e., more than one sentence) G2P transduction.

However, despite their remarkable performance, transformer-based models are affected by *exposure bias*, which is a fundamental issue in auto-regressive generation models [7]. This problem arises due to the discrepancy between the maximum likelihood training (also referred to as teacher forcing [8]) and the generation procedure during inference [9]. As a result, errors can accumulate and propagate throughout the generation process, leading to a significant decrease in performance as the decoded sequence becomes longer.

We show that due to the aforementioned exposure bias, the performance of ByT5 significantly deteriorates when applied to sentence-level G2P tasks due to the model's character-level operation, which leads to longer decoding sequences. This paper proposes a loss-dependent sampling method that builds upon a previously proposed two-pass decoding strategy [10] used to mitigate the exposure bias in Natural Language Processing (NLP). Our method involves identifying positions in the sequence with a high probability of wrong prediction by calculating the cross-entropy loss for each position. The positions with higher loss values are then sampled more frequently during training, in which their predictions are replaced into the ground truth phoneme sequence before inputting into the decoder. By sampling the positions in the sequence where errors are likely to occur during training, the proposed technique allows the model to learn from these errors and improve its ability to correct them. During this process, we use an adaptive sampling ratio determined by the Phoneme Error Rate (PER) of the previous epoch to determine the number of desired replacements adaptively.

With extensive experiments, we show that our loss-dependent sampling method improves the overall performance on our curated English G2P benchmark and quantitatively shows the reduction of exposure bias using the recently proposed metric [9]. Moreover, we present some examples showing improved phoneme prediction due to the mitigation of exposure bias and improved heteronyms prediction over the word-level G2P ByT5.

2. Related work

2.1. Grapheme-to-Phoneme (G2P) Conversion

Early G2P models were based on a pronunciation dictionary, which looked up the corresponding pronunciation of the letter sequence. However, the size of the dictionary had to be very large and costly, and even then, they always had limited coverage with a finite-sized dictionary. Another early approach was the rule-based model, which determines the pronunciation of each letter or the subsequence based on a set of pre-defined phonetic rules [11, 12]. However, designing phonetic rules was often difficult, and still had difficulties capturing irregularities or complex rules, which are frequent in natural languages. To

overcome the limitations of pre-defined phonetic rules, a data-driven stochastic approach that can mitigate complicated phonetic rules from the large dataset was widely used [13, 14, 15]. These approaches usually involve weighted finite state transducers (WFST) [16, 17].

Over time, the G2P conversion studies have shifted to deep learning-based methods [4, 5, 6, 18, 19, 20]. Recently, transformer-based language models have emerged as a powerful tool for the G2P conversion [4, 5, 6] due to their effectiveness in modeling long-term dependencies in sequential data. Notably, the Text-to-Text Transfer Transformer (T5) [3], which has gained attention due to its impressive performance on various NLP tasks, has been widely adapted for the G2P task [5].

2.2. Token-Free Language Model

Recently, token-free models that do not use word tokens have been emerging in NLP, and ByT5 [21] has shown significantly better performance than traditional T5 models by using UTF-8 encoding as input. Because it does not use tokens for corresponding words or subwords, token-free models can process any language, even with unknown vocabulary. This makes it possible to handle a wide variety of languages with high performance, compared to mT5 [22] using multilingual vocabulary embedding. Zhu et al. [6] has used this advantage for multilingual G2P conversion using ByT5.

2.3. Exposure Bias

Despite their significant achievements, transformer-based models suffer from exposure bias, a fundamental problem of auto-regressive natural language generation models [7]. Exposure bias is explained to occur due to the discrepancy between training and test-time generation. During training, the model is trained based on the ground-truth data distribution. On the other hand, the model generates the next token during test time based on the prefix sequences sampled from the model itself. As a result, the error can propagate and accumulate throughout the generation process, leading to a critical degradation in performance, especially when the decoding sequence becomes longer [23]. There have been several attempts to resolve exposure bias in auto-regressive sequence generation model. One way to tackle the problem is to replace or perturb the ground-truth sequence [10, 24]. Some authors claim that the error accumulation can be solved with better decoding methods [25, 26]. Other attempts found the fault in maximum likelihood estimation (MLE) method and took non-MLE based approaches including reinforcement learning [27, 28] or generative adversarial networks [29], while He et al. [30] questions the impact of exposure bias in MLE training.

While it has been an active discussion on whether exposure bias really matters or not, Arora et al. [9] have brought up a quantifiable definition of exposure bias and showed the accumulation of error due to the exposure bias actually exists during natural language generation.

3. Loss-based Sampling

G2P is a sequence-to-sequence task where the input sequence (i.e., grapheme) $\mathbf{X} = [x_0, x_1, x_2, \dots, x_n]$ is transformed to an output phoneme sequence $\mathbf{Y} = [y_0, y_1, y_2, \dots, y_t]$ through a mapping model p_θ , parameterized by θ , in which case we consider using the ByT5 [6].

The training of p_θ is usually done via teacher forcing. The basic idea behind teacher forcing is to train the decoder

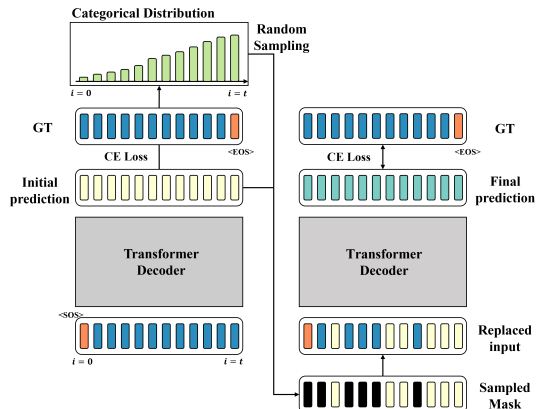


Figure 1: *Our proposed loss-dependent sampling technique. The sampling method identifies positions in the sequence where errors are more likely to occur based on their cross-entropy loss values. By emphasizing these positions during training, the model is encouraged to pay more attention to them, resulting in improved accuracy of the predicted sequence during testing.*

to predict the next phoneme in a sequence given the previous phonemes (context) in that sequence. More formally, the model is trained by minimizing the negative log-likelihood for a given batch B ,

$$\theta^* = \arg \min_{\theta} \frac{-1}{|B|} \sum_{(\mathbf{x}, \mathbf{y}_0^t) \in B} \sum_{i=0}^t \log p_{\theta}(y_i | y_0^{i-1}; \mathbf{X}), \quad (1)$$

where y_i is the phoneme generated at step i , and y_0^{i-1} is the context at time step i . During inference, however, the simplest strategy for generating a target sequence is to auto-regressively sample a sequence. That is, at each step i , pick the most probable phoneme $\hat{y}_i = \arg \max p_{\theta}(\cdot | y_0^{i-1}; \mathbf{X})$. The process carries on until either the sequence length limit is attained, or a unique token representing the end of the sequence (EOS) is produced.

Due to this discrepancy between the training objective and inference generation procedure, also referred to as exposure bias, auto-regressive generation models show degraded performance especially as the sequence of the decoding gets longer.

3.1. Loss-Based Sampling for Exposure Bias Mitigation

Previous work proposed a sampling-based training which involves a two-pass decoding strategy where they randomly mix the gold target sequence with the predicted sequence to mitigate the exposure bias [10]. However, to give positions in the sequence where there is a high probability of wrong prediction during training, we propose a loss-based sampling method (Figure 1).

The method involves several steps, starting with inputting the ground truth phoneme sequence and obtaining the predicted phoneme probability distribution for each time step $i \in [0, t]$,

$$[p_{\theta}(\cdot | y_0^{-1}; \mathbf{X}), p_{\theta}(\cdot | y_0^0; \mathbf{X}), \dots, p_{\theta}(\cdot | y_0^{t-1}; \mathbf{X})]. \quad (2)$$

We then calculate the cross-entropy loss between each of the probability distributions with the one-hot encoding of the ground truth phoneme (note that we do not collect gradients during this step).

$$[\mathbf{H}(p_o, p_{\theta})_0, \mathbf{H}(p_o, p_{\theta})_1, \dots, \mathbf{H}(p_o, p_{\theta})_t], \quad (3)$$

where $H(p_o, p_\theta)_i = \text{CrossEntropy}(\text{onehot}(y_i), p_\theta(\cdot | y_0^{i-1}; \mathbf{X}))$.

Next, we normalize the cross-entropy loss to obtain a categorical distribution. From the distribution, we randomly sample a specific number of time steps without replacement, creating a mask to determine whether to replace each ground truth input with its corresponding prediction. During this sampling process, we use an *adaptive sampling ratio* specified by the Phoneme Error Rate (PER) of the previous epoch to determine the number of desired replacements adaptively. The replaced sequence obtained from the loss-based sampling is once again used as the decoder input. Because the second prediction is generated based on its prediction randomly sampled, the resulting output can reflect the auto-regressive behavior. The cross-entropy loss calculated from the second prediction is our final loss and is used for backpropagation.

The loss-based sampling technique we proposed allows the model to focus during training on positions in the sequence where errors are more likely to occur. By doing so, it can learn from these errors and improve its ability to correct them. This results in improved performance on longer inputs during testing, demonstrating the effectiveness of our approach.

3.2. Evaluation of Exposure Bias

Arora et al. [9] suggested using the time accumulation of the expected per-step prediction losses. During the evaluation, the decoder generates the predicted phoneme probability distribution $p_\theta(\hat{y}_i | \hat{y}_0^{i-1}; \mathbf{X})$ at each step i , based on the previous phoneme sequence \hat{y}_0^{i-1} produced by the decoder. The predicted distribution is compared with the true distribution $p_o(\hat{y}_i | \hat{y}_0^{i-1}; \mathbf{X})$ to yield the per-step auto-regressive prediction loss:

$$l_i^{AR}(\mathbf{X}) = D_{\text{KL}}(p_o(\hat{y}_i | \hat{y}_0^{i-1}; \mathbf{X}) || p_\theta(\hat{y}_i | \hat{y}_0^{i-1}; \mathbf{X})) \quad (4)$$

$$= \sum_{\hat{y}_i \in P} p_o(\hat{y}_i | \hat{y}_0^{i-1}; \mathbf{X}) \log \frac{p_o(\hat{y}_i | \hat{y}_0^{i-1}; \mathbf{X})}{p_\theta(\hat{y}_i | \hat{y}_0^{i-1}; \mathbf{X})}, \quad (5)$$

where P is the set of phonemes. The loss is averaged over the evaluation set D_e to approximate the expected per-step auto-regressive loss:

$$L_i^{AR} \approx \frac{1}{|D_e|} \sum_{(\mathbf{x}, y_0^t) \in D_e} l_i^{AR}(\mathbf{X}). \quad (6)$$

Similarly, the per-step teacher forcing losses are obtained by replacing \hat{y}_0^{i-1} with the ground-truth phoneme sequence y_0^{i-1} , thereby assuming the absence of exposure bias,

$$L_i^{TF} \approx \frac{1}{|D_e|} \sum_{(\mathbf{x}, y_0^t) \in D_e} l_i^{TF}(\mathbf{X}, y_0^t), \quad (7)$$

$$l_i^{TF}(\mathbf{X}, y_0^t) = D_{\text{KL}}(p_o(\hat{y}_i | y_0^{i-1}; \mathbf{X}) || p_\theta(\hat{y}_i | y_0^{i-1}; \mathbf{X})). \quad (8)$$

Then [9] proposed the metric $\text{AccErr}_{\leq}(l)$, defined as the accumulation of the expected auto-regressive prediction loss relative to the expected teacher forcing loss until step l ,

$$\text{AccErr}_{\leq}(l) = l \times \frac{\sum_{i=1}^l L_i^{AR}}{\sum_{i=1}^l L_i^{TF}}. \quad (9)$$

The metric is known to have values between l and l^2 under the proper assumption. The value of l implies the absence of exposure bias for sequences of lengths up to l . On the other hand, a high deviation of $\text{AccErr}_{\leq}(l)$ from l implies a high exposure bias for sequences of length l . In the worst-case scenario, the metric grows quadratically with the phoneme sequence length.

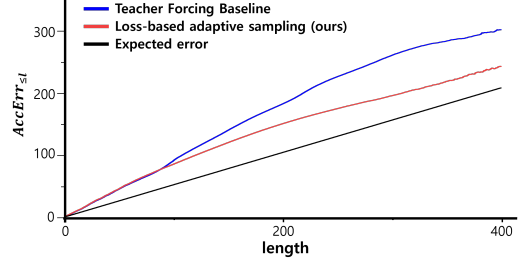


Figure 2: Plot of accumulated error up to length l ($\text{AccErr}_{\le}(l) = l$) w.r.t. l . The Expected Error curve represents the ideal case with no exposure bias.

4. Experimental Settings

4.1. Dataset and Model

TIMIT [31] is a widely used corpus for speech processing tasks such as automatic speech recognition and text-to-speech. TIMIT contains 6300 spoken sentences, 10 by each of the 630 speakers from 8 major dialect regions of US English. TIMIT provides time-aligned orthographic and phonetic transcription, which can be used for labels in G2P conversion. In order to train and evaluate on the sentence-level G2P, we randomly concatenate up to 3 sentences during training. For the test set, we create two subsets, Testset_{short} and Testset_{long} , which contain sentences concatenated up to 3 and 5, respectively. For the model selection, we used ByT5, a token-free model among variants of T5 [21]. For all experiments, we finetune the pre-trained word-level G2P models² [6] based on ByT5-small, which has about 300M parameters.

4.2. Training Details

We use AdamW optimizer [32] with $\beta_1 = 0.9$, $\beta_2 = 0.999$, $\epsilon = 10^{-8}$, and weight decay $\lambda = 5 \times 10^{-3}$. The learning rate is set to 10^{-5} , and the batch size is 32 for all experiments. We use gradient clipping with a 5.0 maximum gradient. The fixed sample ratio is chosen by grid search $\{0, 1, 0.3, 0.6, 0.9\}$, and the best ratio is independently selected for each experiment. The best model is selected by the lowest loss on the validation set. All experiments were done on NVIDIA Quadro RTX 8000.

5. Results

5.1. Experiment Results

Table 1 shows the Phoneme Error Rate (PER) and Word Error Rate (WER) of various sampling methods on different decoding strategies (greedy search and beam search) on the two groups of test set we created (i.e., Testset_{short} and Testset_{long}). The naive two-pass decoding-based sampling method (uniform sampling) performs better than the teacher-forcing baseline. Our loss-based sampling method gives better results than the uniform sampling for both the fixed and adaptive sample ratio settings. Our loss-based sampling with adaptive sample ratio on Testset_{long} obtained 21.99% with greedy search and 21.50% with beam search, outperforming teacher forcing baseline by 2.11%p and 2.15%p, respectively.

In Figure 2, we analyze the exposure bias on teacher forcing baseline and our loss-based adaptive sampling method by plotting the accumulated error with the expected error base on

²<https://github.com/lingjzhu/CharsiuG2P>

9. References

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